PRELIMINARY DATA SHEET

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## **SD1200**

## Analog-Interface XGA/SXGA TFT

## **LCD Display Controller**

September 1998

SmartASIC, Inc.

## SD1200 PRELIMINARY DATA SHEET

## PRSD-1200-A

September 1998

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Document	Revisions	Date
PRSD-1200-A	First Preliminary Datasheet	September 1998

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#### SD1200

Analog-Interface XGA/SXGA TFT LCD Display Controller

#### Features

- Highly integrated analog interface XGA/SXGA TFT LCD Display
  - XGA/SXGA TFT LCD Display ControllerHandle both 24-bit and 48-bit
  - Handle both 24-bit and 48-bit sampled RGB input up to SXGA (1280x1024) @ 85Hz
  - Support various PC graphics cards
  - Drive 48-bit digital RGB output up to SXGA (1280x1024) @ 75Hz
  - Support various TFT LCD panels
  - Truly "Plug and Display" no special driver running on PC
  - Implement proprietary *SmartDisplay* technology for
    - input mode detection and auto calibration
    - output image scaling and interpolation
    - 16.7 million true color support for 6 bit panel
    - robust detection and handling of invalid input modes
  - Advanced input mode detection and auto calibration
    - input refresh rate detection
    - input format detection
    - input sync polarity detection
    - image expansion
    - input frequency detection
    - optimal sampling clock phase calibration
  - Advanced image scaling and interpolation with
    - automatic image centering
    - automatic image expansion in both horizontal and vertical directions

- programmable horizontal and vertical expansion ratio
- programmable horizontal and vertical interpolation algorithm
- True color support for 6 bit panel
  - Proprietary dithering based on both intensity and spatial information
  - Optional frame modulation
- Robust handling of invalid input conditions
  - detect no input signal
  - detect input signal beyond specified acceptable range
  - output status indicators
  - generate output signal even when no input signal
- Support multiple TFT LCD panels
  - programmable output timing parameters to match specifications of various TFT LCD panels
  - support power On/Off sequence
  - Output signal is synchronized with the input signal with the same frame rate
- Low-cost system solution
  - no external frame buffer required
  - 2-wire I<sup>2</sup>C serial interface for EEPROM and CPU
  - programmable OSD mixer
  - direct interface to external ADC's and PLL's
  - 160 pin PQFP Package
  - 5.0V and 3.3V supply



## **1. OVERVIEW**

The SD1200 is an IC designed for analog-interface XGA/SXGA TFT LCD monitors. An analog-interface LCD monitor takes analog RGB signals from a graphic card of a personal computer, the exact same input interface as a conventional CRT monitor. This feature makes analog-interface LCD monitor a true replacement of a conventional CRT monitor.

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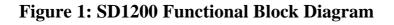
The analog input RGB signals are first sampled by six channels of 8-bit A/D converters, and the 48-bit RGB data are then fed into the SD1200. The SD1200 is capable of performing automatic detection of the display resolution and timing of input signals generated from various PC graphic cards. No special driver is required for the timing detection, nor does any manual adjustment. The SD1200 then automatically scales the input image to fill the full screen of the LCD monitor. The SD1200 can interface with TFT LCD panels from various manufacturers by generating 48-bit RGB signal to the LCD panel based upon the timing parameters saved in the EEPROM.

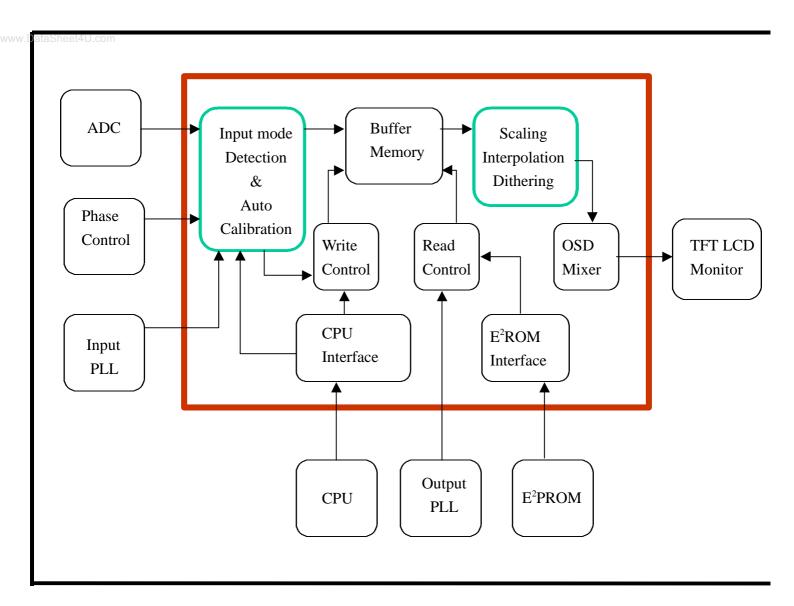
The SD1200 provides two distinguished features to the TFT LCD monitor solution. The first one is "plug-and-play", and the second one is "cost-effective system solution". To be truly plug-and-display, the SD1200 performs automatic input mode detection and auto phase calibration, so that the LCD monitor can ensure the A/D converters' sample clock to be precisely synchronized with the input video data, and to preserve the highest image bandwidth for the highest image quality. Furthermore, the SD1200 can generate output video even when the input signal is beyond the specifications, or no input signal is fed.

For "cost-effective system solution", the SD1200 implements many system support features such as OSD mixer, error status indicators, 2-wire I<sup>2</sup>C serial interface for both EEPROM and host CPU interface, and low-cost IC package. Another important contributing factor is that SD1200 does not require external frame buffer memory for the automatic image scaling and synchronization.

The SD1200 can handle input signal up to SXGA (1280x1024) resolution at 75Hz refresh rate, and produce output signal at SXGA resolution at 75Hz refresh rate (subject to the limitation of LCD panel).

Figure 1 shows the block diagram of the SD1200 as well as the connections of important system components around the SD1200.

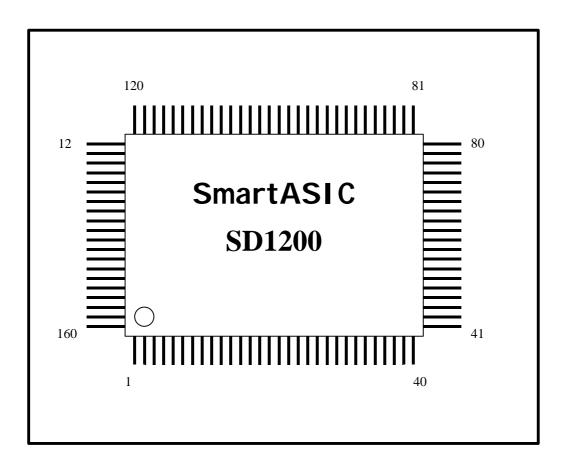




## 2. PIN DESCRIPTION

Figure 2: SD1200 package diagram

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Symbol	PIN Number	Voltage	I/O	Description
B_IN06	1	5	Ι	Input Color Blue
 B_IN07	2	5	Ι	Input Color Blue
B_IN10	3	5	Ι	Input Color Blue
B_IN11	4	5	I	Input Color Blue
B_IN12	5	5	I	Input Color Blue
B_IN13	6	5	I	Input Color Blue
DATA SEL	7	5	I	Select Input Odd/Even Data
B_IN14	8	5	I	Input Color Blue
B_IN15	9	5	I	Input Color Blue
B_IN16	10	5	I	Input Color Blue
B_IN17	10	5	I	Input Color Blue
GND	11	5	1	Ground
HSYNC_I	12	5	Ι	
		5		Input HSYNC (active LOW)
VSYNC_I	14		I	Input VSYNC (active LOW)
MODE_IN0	15	5	Ι	Input Mode Select 1: double 24 bit RGB
MODE INI	16	5	Ι	0: single 24 bit RGB Device ID bit 4 for CPU Interface (Pull
MODE_IN1	16	5	1	
VDD 5V	17	5		High Internally)
VDD_5V			т	+5V Power Supply
MODE_IN2	18	5	Ι	Device ID bit 5 for CPU Interface (Pull
MODE D12	10	5	Ι	High Internally)
MODE_IN3	19	5	1	Device ID bit 6 for CPU Interface (Pull
DOM COL	20	~	0	High Internally)
ROM_SCL	20	5	0	SCL in I <sup>2</sup> C for EEPROM interface
ROM_SDA	21	5	I/O	SDA in I <sup>2</sup> C for EEPROM interface
GND	22	_		Ground
CPU_SCL	23	5	I	SCL in I <sup>2</sup> C for CPU interface
CPU_SDA	24	5	I/O	SDA in I <sup>2</sup> C for CPU interface
PWM_CTL	25	5	0	PWM control signal (Detail description in PWM Operation Section)
CLK_1M	26	5	Ι	Free Running Clock (default: 1MHz)
VDD_5V	27	5		+5V Power Supply
CLK_1M_O	28	5	0	Feedback of free Running Clock
RESET_B	29	5	Ι	System Reset ( active LOW)
R_OSD	30	5	Ι	OSD Color Red
G_OSD	31	5	Ι	OSD Color Green
B_OSD	32	5	Ι	OSD Color Blue
EN_OSD	33	5	I	OSD Mixer Enable
21.000	00	C C	-	=0, No OSD output
				$=1,R_OUT[7:0] = \{R_OSD \text{ repeat } 8 \text{ times}\}$
				G_OUT[7:0]= {G_OSD repeat 8 times }
				B_OUT[7:0]= {B_OSD repeat 8 times }
SCAN_EN	34	5	1	Manufacturing test pin (NC)
	35	5	I	Manufacturing test pin (NC)
			-	
TEST_EN		5	I	Manufacturing test pin (NC)
TEST_EN TEST_H	36	5		Manufacturing test pin (NC) Manufacturing test pin (NC)
TEST_EN		5 5 5	I 0 0	Manufacturing test pin (NC) Manufacturing test pin (NC) Manufacturing test pin (NC)

#### able 1: SD1200 pin description (sorted by pin number)

[					LOW)
	VSYNC_X	40	5	0	Default VSYNC generated by ASIC (active
					LOW)
	GND	41			Ground
	FCLK0	42	5	0	Input PLL Feedback Clock
	VCLK0	43	5	Ι	Input PLL Output Clock
	FCLK1	44	5	0	Output PLL Feedback Clock
Ī	VCLK1	45	5	Ι	Output PLL Output Clock
	HSYNC_O	46	3.3	0	Output HSYNC
	VSYNC_O	47	3.3	0	Output VSYNC
om -	DCLK_OUT	48	3.3	0	Output Clock to Control Panel
-	DE OUT	49	3.3	0	Output Display Enable for Panel (active
	_				HIGH)
	VDD_5V	50	5		+5V Power Supply
	R_OUT0_E	51	3.3	0	Output Color Red Even Pixel
	R_OUT1_E	52	3.3	0	Output Color Red Even Pixel
	R_OUT2_E	53	3.3	0	Output Color Red Even Pixel
	R_OUT3_E	54	3.3	0	Output Color Red Even Pixel
	VDD_3.3V	55	3.3		+3.3V Power Supply
	R_OUT4_E	56	3.3	0	Output Color Red Even Pixel
ŀ	R_OUT5_E	57	3.3	0	Output Color Red Even Pixel
-	R_OUT6_E	58	3.3	0	Output Color Red Even Pixel
-	R_OUT7_E	59	3.3	0	Output Color Red Even Pixel
-	GND	60	5.5	0	Ground
-	R_OUT0_O	61	3.3	0	Output Color Red Odd Pixel
-	R_OUT1_O	62	3.3	0	Output Color Red Odd Pixel
-	R_OUT2_O	63	3.3	0	Output Color Red Odd Pixel
-	R_OUT3_O	64	3.3	0	Output Color Red Odd Pixel
-	VDD_5V	65	5	0	+5V Power Supply
-	R_OUT4_O	66	3.3	0	Output Color Red Odd Pixel
-	R_OUT5_O	67	3.3	0	Output Color Red Odd Pixel
-		68	3.3	0	Output Color Red Odd Pixel
-	R_OUT6_O	<u> </u>	3.3	0	Output Color Red Odd Pixel Output Color Red Odd Pixel
-	R_OUT7_O	70	5.5	0	
-	GND		2.2	0	Ground
-	G_OUT0_E	71	3.3	0	Output Color Green Even Pixel
-	G_OUT1_E	72	3.3	0	Output Color Green Even Pixel
	G_OUT2_E	73	3.3	0	Output Color Green Even Pixel
	G_OUT3_E	74	3.3	0	Output Color Green Even Pixel
-	G_OUT4_E	75	3.3	0	Output Color Green Even Pixel
-	VDD_3.3V	76	3.3		+3.3V Power Supply
	G_OUT5_E	77	3.3	0	Output Color Green Even Pixel
	G_OUT6_E	78	3.3	0	Output Color Green Even Pixel
	G_OUT7_E	79	3.3	0	Output Color Green Even Pixel
	GND	80			Ground
	G_OUT0_O	81	3.3	0	Output Color Green Odd Pixel
	G_OUT1_O	82	3.3	0	Output Color Green Odd Pixel
	G_OUT2_O	83	3.3	0	Output Color Green Odd Pixel
	G_OUT3_O	84	3.3	0	Output Color Green Odd Pixel
	VDD_5V	85	5		+5V Power Supply
[	G_OUT4_O	86	3.3	0	Output Color Green Odd Pixel
ſ	G_OUT5_O	87	3.3	0	Output Color Green Odd Pixel
ſ	G_OUT6_O	88	3.3	0	Output Color Green Odd Pixel
ſ	G_OUT7_O	89	3.3	0	Output Color Green Odd Pixel

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	GND	90			Ground
	B_OUT0_E	91	3.3	0	Output Color Blue Even Pixel
	B_OUT1_E	92	3.3	0	Output Color Blue Even Pixel
Ļ	B_OUT2_E	93	3.3	0	Output Color Blue Even Pixel
	B_OUT3_E	94	3.3	0	Output Color Blue Even Pixel
	B_OUT4_E	95	3.3	0	Output Color Blue Even Pixel
	B_OUT5_E	96	3.3	0	Output Color Blue Even Pixel
	B_OUT6_E	97	3.3	0	Output Color Blue Even Pixel
	VDD_3.3V	98	3.3		+3.3V Power Supply
com	B_OUT7_E	99	3.3	0	Output Color Blue Even Pixel
	GND	100			Ground
	B_OUT0_O	101	3.3	0	Output Color Blue Odd Pixel
L	B_OUT1_O	102	3.3	0	Output Color Blue Odd Pixel
[	B_OUT2_O	103	3.3	0	Output Color Blue Odd Pixel
[	B_OUT3_O	104	3.3	0	Output Color Blue Odd Pixel
[	VDD_5V	105	5		+5V Power Supply
	B_OUT4_O	106	3.3	0	Output Color Blue Odd Pixel
F	B_OUT5_O	107	3.3	0	Output Color Blue Odd Pixel
Γ	B_OUT6_O	108	3.3	0	Output Color Blue Odd Pixel
Γ	B_OUT7_O	109	3.3	0	Output Color Blue Odd Pixel
Γ	GND	110			Ground
Γ	R_IN00	111	5	Ι	Input Color Red
Γ	R_IN01	112	5	Ι	Input Color Red
Γ	R_IN02	113	5	Ι	Input Color Red
F	R_IN03	114	5	Ι	Input Color Red
F	VDD_5V	115	5		+5V Power Supply
Γ	R_IN04	116	5	Ι	Input Color Red
Γ	R_IN05	117	5	Ι	Input Color Red
F	R_IN06	118	5	Ι	Input Color Red
Γ	R_IN07	119	5	Ι	Input Color Red
F	GND	120			Ground
F	R_IN10	121	5	Ι	Input Color Red
F	R_IN11	122	5	Ι	Input Color Red
F	R_IN12	123	5	Ι	Input Color Red
Ē	R_IN13	124	5	Ι	Input Color Red
F	VDD_5V	125	5		+5V Power Supply
F	R_IN14	126	5	Ι	Input Color Red
F	R_IN15	127	5	Ι	Input Color Red
F	R_IN16	128	5	Ι	Input Color Red
F	R_IN17	129	5	Ι	Input Color Red
Ē	GND	130			Ground
F	G_IN00	131	5	Ι	Input Color Green
F	 G_IN01	132	5	Ι	Input Color Green
F	 G_IN02	133	5	Ι	Input Color Green
F	G_IN03	134	5	Ι	Input Color Green
F	VDD_5V	135	5		+5V Power Supply
F	G_IN04	136	5	Ι	Input Color Green
F	G_IN05	137	5	I	Input Color Green
F	ADC_CLK0	138	5	0	Sample Clock for ADC 0
1		139	5	I	Input Color Green
ſ	G IN06				
-	G_IN06 G_IN07	140	5	Ι	Input Color Green

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	G_IN10	142	5	Ι	Input Color Green
	G_IN11	143	5	Ι	Input Color Green
	ADC_CLK1	144	5	0	Sample Clock for ADC 1
	G_IN12	145	5	Ι	Input Color Green
	G_IN13	146	5	Ι	Input Color Green
	VDD_5V	147	5		+5V Power Supply
	G_IN14	148	5	Ι	Input Color Green
	G_IN15	149	5	Ι	Input Color Green
	G_IN16	150	5	Ι	Input Color Green
m	G_IN17	151	5	Ι	Input Color Green
	GND	152			Ground
	B_IN00	153	5	Ι	Input Color Blue
	B_IN01	154	5	Ι	Input Color Blue
	B_IN02	155	5	Ι	Input Color Blue
	B_IN03	156	5	Ι	Input Color Blue
	VDD_5V	157	5		+5V Power Supply
	B_IN04	158	5	Ι	Input Color Blue
	B_IN05	159	5	Ι	Input Color Blue
	GND	160			Ground

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Sy	mbol	PIN Number	Voltage	I/O	Description
	IN00	111	5	Ι	Input Color Red
	IN01	112	5	Ι	Input Color Red
	IN02	113	5	Ι	Input Color Red
R	IN03	114	5	Ι	Input Color Red
	IN04	116	5	Ι	Input Color Red
	IN05	117	5	Ι	Input Color Red
	IN06	118	5	I	Input Color Red
	IN07	119	5	Ι	Input Color Red
	IN10	121	5	Ι	Input Color Red
	IN11	122	5	I	Input Color Red
	IN12	123	5	I	Input Color Red
	IN13	124	5	I	Input Color Red
	IN14	126	5	I	Input Color Red
	IN15	120	5	I	Input Color Red
	IN16	127	5	I	Input Color Red
	IN17	120	5	I	Input Color Red
	IN00	129	5	I	Input Color Green
	IN00 IN01	131	5	I	Input Color Green
	IN01 IN02	132	5	I	Input Color Green
	IN02 IN03	133	5	I	Input Color Green
	IN03 IN04	134	5	I	Input Color Green
	IN04 IN05	130	5	I	Input Color Green
	IN05 IN06	137	5	I	Input Color Green
	IN06 IN07	139	5	I	1
	IN07 IN10	140	5		Input Color Green Input Color Green
				I	*
	<u>IN11</u>	143	5 5	I	Input Color Green
	IN12	145	5	I	Input Color Green
	<u>IN13</u>	146		I	Input Color Green
	<u>IN14</u>	148	5	I	Input Color Green
	<u>IN15</u>	149	5	I	Input Color Green
	<u>IN16</u>	150	5	I	Input Color Green
	<u>IN17</u>	151	5	I	Input Color Green
	IN00	153	5	Ι	Input Color Blue
	IN01	154	5	Ι	Input Color Blue
	IN02	155	5	Ι	Input Color Blue
	IN03	156	5	Ι	Input Color Blue
	IN04	158	5	Ι	Input Color Blue
	IN05	159	5	Ι	Input Color Blue
	IN06	1	5	Ι	Input Color Blue
	IN07	2	5	Ι	Input Color Blue
B_	IN10	3	5	Ι	Input Color Blue
B_	IN11	4	5	Ι	Input Color Blue
B_	IN12	5	5	Ι	Input Color Blue
B_	IN13	6	5	Ι	Input Color Blue
B_	IN14	8	5	Ι	Input Color Blue
	IN15	9	5	Ι	Input Color Blue
	IN16	10	5	Ι	Input Color Blue
D					

#### Table 2: SD1200 pin description (sorted by function)

Г					
-	HSYNC_I	13	5	Ι	Input HSYNC (active LOW)
-	VSYNC_I	14	5	Ι	Input VSYNC (active LOW)
-	MODE_IN0	15	5	I	Input Mode Select
			-	_	1: double 24 bit RGB
					0: single 24 bit RGB
	MODE_IN1	16	5	Ι	Device ID bit 4 for CPU Interface (Pull
	_				High Internally)
	MODE_IN2	18	5	Ι	Device ID bit 5 for CPU Interface (Pull
					High Internally)
neet4U.com	MODE_IN3	19	5	Ι	Device ID bit 6 for CPU Interface (Pull
					High Internally)
	ADC_CLK0	138	5	0	Sample Clock for ADC 0
	ADC_CLK1	144	5	0	Sample Clock for ADC 1
	R_OUT0_E	51	3.3	0	Output Color Red Even Pixel
	R_OUT1_E	52	3.3	0	Output Color Red Even Pixel
	R_OUT2_E	53	3.3	0	Output Color Red Even Pixel
	R_OUT3_E	54	3.3	0	Output Color Red Even Pixel
	R_OUT4_E	56	3.3	0	Output Color Red Even Pixel
	R_OUT5_E	57	3.3	0	Output Color Red Even Pixel
	R_OUT6_E	58	3.3	0	Output Color Red Even Pixel
	R_OUT7_E	59	3.3	0	Output Color Red Even Pixel
	R_OUT0_O	61	3.3	0	Output Color Red Odd Pixel
	R_OUT1_O	62	3.3	0	Output Color Red Odd Pixel
	R_OUT2_O	63	3.3	0	Output Color Red Odd Pixel
	R_OUT3_O	64	3.3	0	Output Color Red Odd Pixel
	R_OUT4_O	66	3.3	0	Output Color Red Odd Pixel
	R_OUT5_O	67	3.3	0	Output Color Red Odd Pixel
	R_OUT6_O	68	3.3	0	Output Color Red Odd Pixel
	R_OUT7_O	69	3.3	0	Output Color Red Odd Pixel
	G_OUT0_E	71	3.3	0	Output Color Green Even Pixel
	G_OUT1_E	72	3.3	0	Output Color Green Even Pixel
	G_OUT2_E	73	3.3	0	Output Color Green Even Pixel
	G_OUT3_E	74	3.3	0	Output Color Green Even Pixel
	G_OUT4_E	75	3.3	0	Output Color Green Even Pixel
	G_OUT5_E	77	3.3	0	Output Color Green Even Pixel
	G_OUT6_E	78	3.3	0	Output Color Green Even Pixel
	G_OUT7_E	79	3.3	0	Output Color Green Even Pixel
	G_OUT0_O	81	3.3	0	Output Color Green Odd Pixel
	G_OUT1_O	82	3.3	0	Output Color Green Odd Pixel
	G_OUT2_O	83	3.3	0	Output Color Green Odd Pixel
	G_OUT3_O	84	3.3	0	Output Color Green Odd Pixel
	G_OUT4_O	86	3.3	0	Output Color Green Odd Pixel
	G_OUT5_O	87	3.3	0	Output Color Green Odd Pixel
[	G_OUT6_O	88	3.3	0	Output Color Green Odd Pixel
-	G_OUT7_O	89	3.3	0	Output Color Green Odd Pixel
	B_OUT0_E	91	3.3	0	Output Color Blue Even Pixel
	B_OUT1_E	92	3.3	0	Output Color Blue Even Pixel
	B_OUT2_E	93	3.3	0	Output Color Blue Even Pixel

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-				-	1
Ļ	B_OUT3_E	94	3.3	0	Output Color Blue Even Pixel
L	B_OUT4_E	95	3.3	0	Output Color Blue Even Pixel
	B_OUT5_E	96	3.3	0	Output Color Blue Even Pixel
L	B_OUT6_E	97	3.3	0	Output Color Blue Even Pixel
	B_OUT7_E	99	3.3	0	Output Color Blue Even Pixel
	B_OUT0_O	101	3.3	0	Output Color Blue Odd Pixel
	B_OUT1_O	102	3.3	0	Output Color Blue Odd Pixel
	B_OUT2_O	103	3.3	0	Output Color Blue Odd Pixel
	B_OUT3_O	104	3.3	0	Output Color Blue Odd Pixel
	B_OUT4_O	106	3.3	0	Output Color Blue Odd Pixel
m	B_OUT5_O	107	3.3	0	Output Color Blue Odd Pixel
	B_OUT6_O	108	3.3	0	Output Color Blue Odd Pixel
	B_OUT7_O	109	3.3	0	Output Color Blue Odd Pixel
		,		-	
	HSYNC_O	46	3.3	0	Output HSYNC
F	VSYNC_0	47	3.3	0	Output VSYNC
-	DCLK_OUT	48	3.3	0	Output VSTICE Output Clock to Control Panel
-	DELK_001 DE_OUT	48	3.3	0	Output Display Enable for Panel (active
	DE_001	49	5.5	0	HIGH)
-					
-	ECI KO	42	5	0	Innut DLL Eachbook Clock
-	FCLK0	42	5	0	Input PLL Feedback Clock
-	VCLK0	43	5	I	Input PLL Output Clock
-	FCLK1	44	5	0	Output PLL Feedback Clock
F	VCLK1	45	5	Ι	Output PLL Output Clock
-	<b>DOL 60</b>	• •			
-	ROM_SCL	20	5	0	SCL in I <sup>2</sup> C for EEPROM interface
L	ROM_SDA	21	5	I/O	SDA in I <sup>2</sup> C for EEPROM interface
L					2
L	CPU_SCL	23	5	Ι	SCL in I <sup>2</sup> C for CPU interface
	CPU_SDA	24	5	I/O	SDA in I <sup>2</sup> C for CPU interface
	PWM_CTL	25	5	0	PWM control signal (Detail description in
					PWM Operation Section)
L	CLK_1M	26	5	Ι	Free Running Clock (default: 1MHz)
L	CLK_1M_O	28	5	0	Feedback of free Running Clock
	RESET_B	29	5	Ι	System Reset ( active LOW)
	HSYNC_X	39	5	0	Default HSYNC generated by ASIC (active
					LOW)
	VSYNC_X	40	5	0	Default VSYNC generated by ASIC (active
					LOW)
F	R_OSD	30	5	Ι	OSD Color Red
			5	I	OSD Color Green
Γ	G_OSD	31	5		
-	G_OSD B_OSD				OSD Color Blue
	B_OSD	32	5	Ι	OSD Color Blue OSD Mixer Enable
-					OSD Mixer Enable
-	B_OSD	32	5	Ι	OSD Mixer Enable =0, No OSD output
-	B_OSD	32	5	Ι	OSD Mixer Enable =0, No OSD output =1,R_OUT[7:0]= {R_OSD repeat 8 times}
-	B_OSD	32	5	Ι	OSD Mixer Enable =0, No OSD output =1,R_OUT[7:0]= {R_OSD repeat 8 times} G_OUT[7:0]= {G_OSD repeat 8 times }
-	B_OSD	32	5	Ι	OSD Mixer Enable =0, No OSD output =1,R_OUT[7:0]= {R_OSD repeat 8 times}
-	B_OSD	32	5	Ι	OSD Mixer Enable =0, No OSD output =1,R_OUT[7:0]= {R_OSD repeat 8 times} G_OUT[7:0]= {G_OSD repeat 8 times }

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### PRELIMINARY DATA SHEET

FAIL_H	38	5	0	Manufacturing test pin (NC)
TST_DON		5	0	Manufacturing test pin (NC)
TEST EN		5	I	Manufacturing test pin (NC)
	55	5	1	Wanufacturing test pin (NC)
DATA_SE	L 7	5	Ι	Select Input Odd/Even Data
VDD_5V	17	5		+5V Power Supply
VDD_5V		5		+5V Power Supply
VDD_5V	50	5		+5V Power Supply
VDD_5V		5		+5V Power Supply
VDD_5V	85	5		+5V Power Supply
VDD_5V		5		+5V Power Supply
VDD_5V		5		+5V Power Supply
VDD_5V	125	5		+5V Power Supply
VDD_5V	135	5		+5V Power Supply
VDD_5V	147	5		+5V Power Supply
VDD_5V	157	5		+5V Power Supply
VDD_3.3V		3.3		+3.3V Power Supply
VDD_3.3V		3.3		+3.3V Power Supply
VDD_3.3V	/ 98	3.3		+3.3V Power Supply
GND	12			Ground
GND	22			Ground
GND	41			Ground
GND	60			Ground
GND	70			Ground
GND	80			Ground
GND	90			Ground
GND	100			Ground
GND	110			Ground
GND	120			Ground
GND	130			Ground
GND	141			Ground
GND	152			Ground
GND	160			Ground

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## **3. FUNCTIONAL DESCRIPTION**

The SD1200 has the following major function blocks:

- 1. Input mode detection & auto calibration block
- 2. Buffer memory and read/write control block
- 3. Image scaling, interpolation and dithering block
- 4. OSD mixer and LCD interface block
- 5. EEPROM interface block
- 6. CPU interface block

The following sections will describe the functionality of these blocks.

#### **3.1.** Input mode detection & auto calibration block

#### **3.1.1.** Supported input modes

The SD1200 accepts seven different input video modes:

- 640 x 350
- 640 x 400
- 720 x 400
- 640 x 480 (VGA)
- 800 x 600 (SVGA)
- 1024 x 768 (XGA)
- 1280 x 1024 (SXGA)

There is no frame rate restriction on the input modes. However, since the output signal is synchronized with the input signal at the same refresh rate. The input refresh rate has to be within the acceptable range of the LCD panel.

#### **3.1.2.** Input mode detection

The SD1200 can automatically detect the mode of the input signal without any user adjustment or driver running on the PC host or external CPU. This block

automatically detects polarity of input synchronization and the sizes of back porch, valid data window and the synchronization pulse width in both vertical and horizontal directions. The size information is then used not only to decide the input resolution, to generate the frequency divider for the input PLL, to lock the PLL output clock with HSYNC, but also to automatically scale the image to full screen, and to synchronize the output signal with the input signal.

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The detection logic is always active to automatically detect any changes to the input mode. Users can manually change the input mode information at run time through the CPU interface. Detail operation of the CPU interface is described in Section. "CPU Interface".

#### **3.1.3.** Auto calibration

The SD1200 can automatically calibrate the phase of the sample clock in order to preserve the bandwidth of input signal and get the best quality. The SD1200 implements a proprietary image quality function. During auto-calibration process, the SD1200 continues search for the best phase to optimize the image quality.

The output image may display some jitter and blurring during the auto-calibration process, and the image will become crisp and sharp once the optimum phase is found. User can change the sampling clock phase value by the external CPU. Detail operation of the CPU interface is described in Section. "CPU Interface".

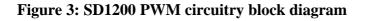
The auto calibration process can be delayed and even disabled by the external CPU if system designer wants to have his/her own implementation.

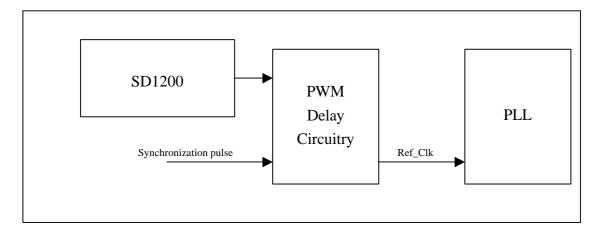
#### **3.1.4. PWM operation**

The SD1200 implements a very unique algorithm to adjust the phase of the A/D converter's sampling clock. An external delay circuitry is required to compliment the SD1200 for the auto-calibration process. The SD1200 generates a Pulse-Width Modulated (PWM) signal to the external delay circuitry. The delay circuitry should insert a certain amount of time delay synchronization pulse based upon the width of the PWM signal. A brief circuit diagram for the PWM is shown in Figure 3.

The PWM signal from the SD1200 is a periodical signal with a period that is 511

times of the period of the free-running clock connected to the pin "CLK\_1M". System manufacturers may select any frequency for the free running clock. The default clock frequency is 1MHz. System manufacturers also decide the unit delay for the external delay circuitry. The delay information is stored in the EEPROM. When the SD1200 wants to delay the synchronization pulse for N units of delay, it will output the PWM with the high time equal to (N \* the period of the free-running clock), and with low time equal to (511-N)\* the period of the free-running clock. When N=511, the PWM signal stays high all the time, and when N=0, the PWM signal is always low.





#### 3.1.5. Free Running Clock

As described in previous section, a free-running clock is needed for the SD1200. This clock is used for many of the SD1200's internal operations. PWM operation is one of them. System manufacturers can select the frequency of the free-running clock, and the default clock frequency is 1MHz. System manufacturer can use an oscillator to generate the free-running clock, and feed that clock directly to the pin "CLK\_1M", or use a crystal connecting to "CLK\_1M" and "CLK\_1M\_O".

#### **3.2. Buffer memory and read/write control block**

The SD1200 uses internal buffer memory to store a portion of the input image for image scaling and output synchronization. No external memory buffer is needed for the SD1200. The write control logic ensures the input data are stored into the right area of the buffer memory, and the read control logic is responsible to fetch the data from the buffer memory from the correct area and at the correct timing sequence. With the precise timing control of the write and read logic, the output image is appropriately scaled to the full screen, and the output signal is perfectly synchronized with the input signals.

#### **3.3.** Image scaling, interpolation and dithering block

The SD1200 supports both automatic image scaling and interpolation.

#### **3.3.1.** Image scaling

The SD1200 supports several different input modes, and the input image may have different sizes. It is essential to support automatic image scaling so that the input image is always displayed to the full screen regardless the input mode. The SD1200 scale the images in both horizontal and vertical directions. It calculates the correct scaling ratio for both directions based upon the LCD panel resolution, and the input mode and timing information produced by the "Input mode detection & auto calibration" block. The scaling ratio is re-adjusted whenever a different input mode is detected. The ratio is then fed to the buffer memory read control logic to fetch the image data with the right sequence and timing. Some of the image data may be read more than once to achieve scaling effect.

#### **3.3.2.** Image interpolation

The SD1200 supports image interpolation to achieve better image quality. A basic image scaling algorithm replicates the input images to achieve the scaling effect. The replication scheme usually results in a poor image quality. The SD1200 implements both linear interpolation and a proprietary interpolation algorithm. Through external micro-controller, users can chose among different interpolation algorithm.

#### 3.3.3. Dithering

The SD1200 supports 16.7 million true colors for 6-bit panel. Two dithering algorithms are implemented and again users can chose between them through the external micro-controller.

### www.DataSheet4U.com **3.4. OSD mixer and LCD interface**

At the output stage, the SD1200 performs the OSD mixer function, and then generates 24-bit RGB signal to the LCD panel with the correct timing.

#### 3.4.1. OSD mixer

In the OSD mixer block, the SD1200 mixes the normal output RGB signal with the OSD signal. The OSD output data is generated based on the "R\_OSD", "G\_OSD" and "B\_OSD" pins as well as the "OSD Intensity" data in EEPROM entry. When the "EN\_OSD" is active high, the OSD is active, and the SD1200 will send the OSD data to the LCD panel. The OSD has 16 different color schemes based on the combinations of the three OSD color pins and the "OSD Intensity" data. When R\_OSD=1, and OSD\_Intensity=0, the SD1200 will output 128 to the output red channel, R\_OUT. When R\_OSD=1, and OSD\_Intensity=1, the SD1200 will output 255. The same scheme is used for G\_OSD to G\_OUT and for B\_OSD to B\_OUT.

#### **3.4.2.** LCD interface

The SD1200 support 48-bit RGB interface with XGA/SXGA LCD panels from various panel manufacturers. The LCD panel resolution and timing information is stored in the external EEPROM. The information in the EEPROM includes timing related to the output back porch, synchronization pulse width and valid data window. The timing information is used to generate the frequency divider for the output PLL, to lock the PLL output clock with HSYNC for the LCD data clock, and to synchronized the output VSYNC and input VSYNC.

### **3.5. EEPROM interface**

As mentioned in previous sections, the external EEPROM stores much crucial information for the SD1200 internal operations. The SD1200 interfaces with the EEPROM through a 2-wire I<sup>2</sup>C serial interface. The suggested EEPROM device is an industry standard serial-interface EEPROM (24x08). The I<sup>2</sup>C interface scheme is briefly described here and detail description can be found in many public literatures.

#### **3.5.1. I**<sup>2</sup>**C** serial interface

The I<sup>2</sup>C serial interface used 2 wires, SCL and SDA. The SCL is driven by the SD1200, and used mainly as the sampling clock and the SDA is a bi-directional signal and used mainly for data signal. Figure 4 shows the basic bit definitions of I<sup>2</sup>C serial interface.

The I<sup>2</sup>C serial interface supports random read and sequential read operations. Figure 5 and 6 shows the data sequences for random read and sequential read operations.

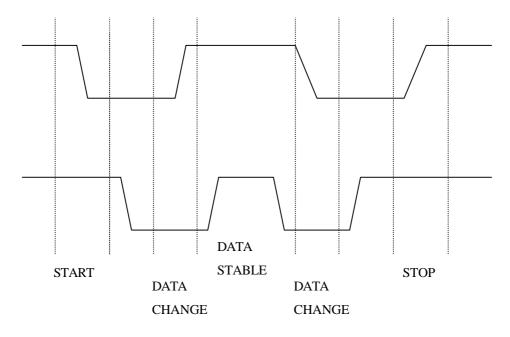
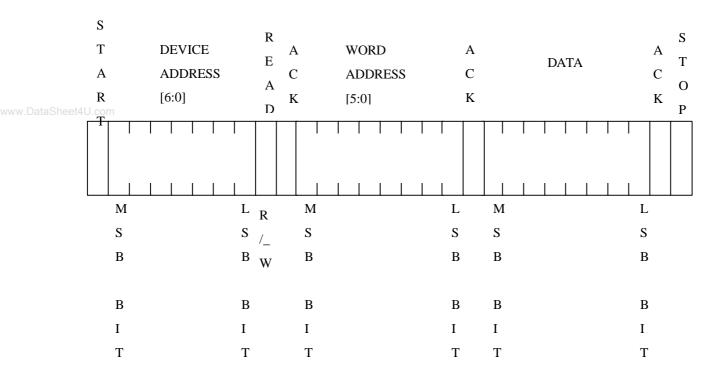
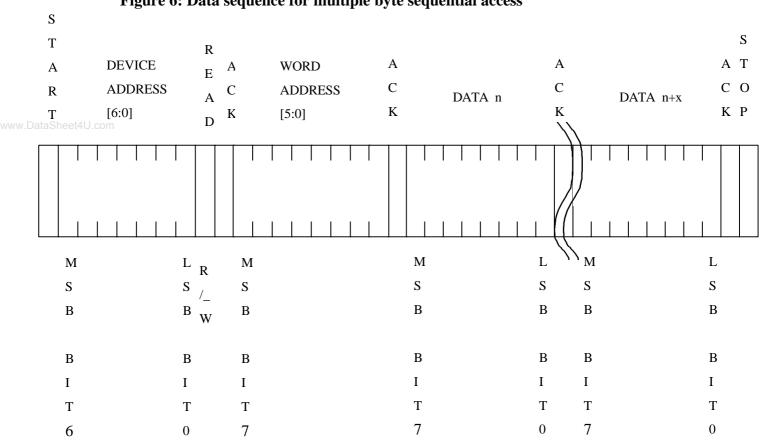


Figure 4: START, STOP AND DATA Definitions in I<sup>2</sup>C serial interface



#### Figure 5: Data sequence for single byte random access



#### Figure 6: Data sequence for multiple byte sequential access

#### **3.5.2. EEPROM** Contents

The contents of EEPROM are primarily dependent on the specifications of the LCD panel. SmartASIC provides suggested EEPROM contents for LCD panels from various panel manufacturers. The section presents all the entries in the EEPROM, and briefly describes their definitions. That allows the system manufacturers to have their own EEPROM contents to distinguish their monitors.

The EEPROM contents can be partitioned into 11 parts. The first 8 parts are input mode dependent. When the SD1200 detects the input mode, it will then load the information related to the detected mode from the EEPROM. The information in the 9<sup>th</sup> part is mainly for input mode detection as well as some threshold values for error status indicators. The 10<sup>th</sup> and 11<sup>th</sup> parts are look up table for interpolation parameters. The 9<sup>th</sup>, 10<sup>th</sup> and 11<sup>th</sup> parts are loaded in the SD1200 during the reset time.

- Part 1: 640x350 mode,
- Part 2: 640x400 mode,
- Part 3: 720x400 mode,
- Part 4: 640x480 mode,
- Part 5: 800x600 mode,
- Part 6: 1024x768 mode,
- Part 7: 1280x1024 mode, and
- Part 8: user defined mode
- Part 9: input mode detection and scaling related parameters
- Part 10: lookup table for horizontal interpolation
- Part 11: lookup table for vertical interpolation

#### Part 1-8: Input Mode Dependent Data

Symbol	W	640								Description
		x 350	x 400	x 400	x 480	x 600	x 768	x 1024	ALI D	
VPW	11					80H				LCD VSYNC pulse width
	••						A1H			
VBP	11					82H				LCD VSYNC back porch
		03H	23H	43H	63H	83H	A3H	C3H		(including VPW)
VBP Source	11						A4H			LCD VSYNC back porch (source
		05H	25H	45H	65H	85H	A5H	C5H	E5H	equivalent)
										= VBP * Line Expansion and round
Tongot Shin	11	0611	2611	1611	<u> </u>	0211	A6H	C6H	E4H	up If VBP can not be converted into
Target Skip Pixel	11						А6Н А7Н			source evenly, the leftover is
r ixei		0/11	2711	4/11	0/11	0/11	A/II	C/II	E/II	converted into number of pixels
VSIZE	11	08H	28H	48H	68H	88H	A8H	C8H	E8H	LCD number of lines
							A9H			
HPW	11									LCD HSYNC pulse width
		0BH	2BH	4BH	6BH	8BH	ABH	CBH	EBH	_
HBP	11									LCD HSYNC back porch(including
										HPW)
HSIZE	11						AEH			LCD number of columns
							AFH			
HTOTAL	11						B0H			LCD total number of pixels per line
	10						B1H			including all porches
HTOTAL Source	12					92H 93H				LCD total number of clocks per line (source equivalent) =
Source		1511	5511	5511	/311	9511	DJII	D3II	1.211	HTOTAL/Line Expansion
Line	4	14H	34H	54H	74H	94H	B4H	D4H	F4H	Vertical source to destination
Expansion	•						[6:3]			scaling factor
1										0: 1 to 1
										1: 2 to 3
										2: 3 to 4
										3: 5 to 8
										4: 15 to 32
										5: 25 to 32 6: 25 to 48
										7: 25 to 64
										8: 75 to 128
										9: 175 to 384
										10: 175 to 512
Pixel	3						B4H			Horizontal source to destination
Expansion		[2:0]	[2:0]	[2:0]	[2:0]	[2:0]	[2:0]	[2:0]	[2:0]	scaling factor
										0: 1 to 1
										1: 2 to 4
										2: 4 to 5 3: 25 to 36
										4: 5 to 8
										5: 9 to 10
										6: 45 to 64
										7: 9 to 16

#### PRELIMINARY DATA SHEET

Fog Factor Horizontal815H35H55H75H95HB5HD5HF5HHorizontal fogging factorFog Factor 2X816H36H56H76H96HB6HD6HF6HDouble of Horizontal fogging factorYertical817H37H57H77H97HB7HD7HF7HVertical fogging factorMinimum input lines1118H38H58H78H98HB8HD8HF8HMinimum input lines = (VSIZE + VBP)* Line Expansion When the input has fewer lines than this value, it is considered as an ERROR, and INPUT_X status bit will be HIGH.Maximum input pixels111AH3AH5AH7AH9AHBAHDAHFAH BBHMaximum input pixels per line.Maximum input pixels111AH3AH5AH7AH9AHBAH BBHDAH BBHFAH BBHMaximum input pixels per line.Maximum input pixels111AH3AH5AH BH7AH9AH BBHBAH BBHDAH BBHFAH BBHMaximum input pixels per line.Source31CH3CH5CH7CH9CHBCHDCHFCHSource horizontal size upper 3 bitsVSIZE[11:8][6:4][6:4][6:4][6:4][6:4][6:4][6:4][6:4][6:4]Source31CH3CH5CH7CH9CHBCHDCHFCHSource horizontal size upper 3 bitsVSIZE[11:8]<											
2XImage: constraint of the second stress of the		8	15H	35H	55H	75H	95H	B5H	D5H	F5H	Horizontal fogging factor
VerticalImage: Second Seco	-	8	16H	36H	56H	76H	96H	B6H	D6H	F6H	Double of Horizontal fogging factor
input lines19H39H59H79H99HB9HD9HF9H(VSIZE + VBP)* Line Expansion When the input has fewer lines than this value, it is considered as an ERROR, and INPUT_X status bit will be HIGH.Maximum input pixels11IAH3AH5AH7AH9AHBAH PBHDAH PBHFAH DBHMaximum input pixels per line. Auto clock recovery will not set input PLL divisor larger than this value.Source3ICH3CH5CH7CH9CHBCH PCHDCHFCH [6:4]Source horizontal size upper 3 bitsSource3ICH3CH5CH7CH9CHBCH PCHDCHFCH [6:4]Source horizontal size upper 3 bitsSource3ICH3CH5CH7CH9CHBCH PCHDCHFCH FCHSource horizontal size upper 3 bitsVSIZE[11:8][2:0][2:0][2:0][2:0][2:0][2:0][2:0]Source8IDH3DH5DH7DH9DHBDHDDHFDHSource horizontal size lower 8 bitsSource8IEH3EH5EH7EH9EHBEHDEHFEHSource vertical size lower 8 bitsSource8IEH3EH5FH7FH9FHBFHDFHFFHSum of above 31 bytes (keep lowerCheck sum8IFH3FH5FH7FH9FHBFHDFHFFHSum of above 31 bytes (keep lower	-	8	17H	37H	57H	77H	97H	B7H	D7H	F7H	Vertical fogging factor
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Source HSIZE[7:0]81DH3DH5DH7DH9DHBDHDDHFDHSource horizontal size lower 8 bitsSource VSIZE[7:0]81EH3EH5EH7EH9EHBEHDEHFEHSource vertical size lower 8 bitsVSIZE[7:0]Check sum81FH3FH5FH7FH9FHBFHDFHFFHSum of above 31 bytes (keep lower	Source	3	1CH	3CH	5CH	7CH	9CH	BCH	DCH	FCH	Source vertical size upper 3 bits
HSIZE[7:0]       Image: Constraint of the symbol of the symb	VSIZE[11:8]		[2:0]	[2:0]	[2:0]	[2:0]	[2:0]	[2:0]	[2:0]	[2:0]	
Source       8       1EH       3EH       5EH       7EH       9EH       BEH       DEH       FEH       Source vertical size lower 8 bits         VSIZE[7:0] </td <td>Source</td> <td>8</td> <td>1DH</td> <td>3DH</td> <td>5DH</td> <td>7DH</td> <td>9DH</td> <td>BDH</td> <td>DDH</td> <td>FDH</td> <td>Source horizontal size lower 8 bits</td>	Source	8	1DH	3DH	5DH	7DH	9DH	BDH	DDH	FDH	Source horizontal size lower 8 bits
VSIZE[7:0]	HSIZE[7:0]										
Check sum 8 1FH 3FH 5FH 7FH 9FH BFH DFH FFH Sum of above 31 bytes (keep lower	Source	8	1EH	3EH	5EH	7EH	9EH	BEH	DEH	FEH	Source vertical size lower 8 bits
	VSIZE[7:0]										
8 bits only)	Check sum	8	1FH	3FH	5FH	7FH	9FH	BFH	DFH	FFH	Sum of above 31 bytes (keep lower
											8 bits only)

#### **Part 9: Input Mode Detection Data**

Symbol	Width (bits)	Address	Description
Data low threshold	8	120H	Low water mark for valid data
			If the data is smaller than this threshold, it is
			considered LOW internally
Data high threshold	8	121H	High water mark for valid data
			If the data is larger than this threshold, it is considered
			HIGH internally
Edge threshold	8	122H	Minimum difference between the data value of two
			adjacent pixels to be considered as an edge
Calibration mode	2	123H [1:0]	This is to select different operation modes of internal
			phase calibration. The selection criterion is as follow:
			0: when input video signal has large overshot,
			it results in longest calibration time
			1: when input video signal has median overshot,
			it results in long calibration time
			2: when input video signal has normal overshot,
			it results in normal calibration time
			(recommended)
			3: when input video signal has no overshot,
			it results in shortest calibration time
Res0 threshold	10	124H-125H	Upper bound of the line number for 640x350 mode,
			and lower bound for 640x400
Res1 threshold	10	126H-127H	Upper bound of the line number for 640x400 mode,

				and lower bound for 720x400
	Res2 threshold	10	12011 12011	
	Res2 threshold	10	128H-129H	Upper bound of the line number for $720x400$ mode,
		10	10.111.10011	and lower bound for 640x480
	Res3 threshold	10	12AH-12BH	Upper bound of the line number for 640x480 mode,
				and lower bound for 800x600
	Res4 threshold	10	12CH-12DH	Upper bound of the line number for 800x600 mode,
				and lower bound for 1024x768
	Res5 threshold	10	12EH-12FH	Upper bound of the line number for 1024x768 mode,
				and lower bound for 1280x1024
	Res6 threshold	10	130H-131H	Upper bound of the line number for 1280x1024 mode
	reso unesnora	10	10011 10111	If the input has more line than this threshold, it is
				considered INVALID mode
-	Mode 640x350	2	120111.01	
		Z	132H[1:0]	The polarity of input synchronization signals
	Sync Polarity			Bit 0 is for VSYNC and bit 1 is for HSYNC
	Mode 640x400	2	132H[3:2]	The polarity of input synchronization signals
	Sync Polarity			Bit 0 is for VSYNC and bit 1 is for HSYNC
	Mode 720x400	2	132H[5:4]	The polarity of input synchronization signals
	Sync Polarity			Bit 0 is for VSYNC and bit 1 is for HSYNC
	Mode 640x480	2	132H[7:6]	The polarity of input synchronization signals
	Sync Polarity			Bit 0 is for VSYNC and bit 1 is for HSYNC
	Mode 800x600	2	133H[1:0]	The polarity of input synchronization signals
	Sync Polarity		[ ]	Bit 0 is for VSYNC and bit 1 is for HSYNC
	Mode 1024x768	2	133H[3:2]	The polarity of input synchronization signals
	Sync Polarity	2	15511[5.2]	Bit 0 is for VSYNC and bit 1 is for HSYNC
-	Mode 1280x1024	2	133H[5:4]	The polarity of input synchronization signals
		2	1556[5.4]	Bit 0 is for VSYNC and bit 1 is for HSYNC
_	Sync Polarity	0	10411	
	Maximum VBP	8	134H	The maximum vertical back porch for input video
	PWM unit delay	13	135H-136H	The unit delay used in the external PWM delay
				circuitry. If the free-running clock is 1MHz, and the
				intended unit delay is 0.2 ns (= 5,000MHz), then a
				value of $5,000$ MHz/1MHz = $5,000$ is used here.
	Maximum link off	22	137H-139H	Maximum time when input VSYNC is off before the
	time			LINK_DWN pin turns ON (unit: clock period of the
				free running clock). If the free-running clock is
				1MHz, and the intended maximum time is 1 second,
				then a value of $1,000,000 \text{ us}/1 \text{ us} = 1,000,000 \text{ is used}$
				here.
	Maximum refresh	16	13AH-13BH	Maximum refresh rate supported by the LCD panel
	rate	10	10/11/10/211	If the intended maximum refresh rate is 75Hz, and the
	Tuto			free-running clock is 1MHz, then a value of
				1000000/75=133,333 is used here
-	Movimum input	8	13CH	Maximum source clock rate supported by the SD1200
	Maximum input	0	посп	
	frequency			(unit: frequency of free-running clock)
				If the intended maximum clock rate is 60MHz, and
				the free-running clock is 1MHz, then a value of 60 is
				used here.
				If the input signal has a higher frequency than this
				value, the VCLK0_X status bit will turn ON.
_	Scale factor CE	8	13DH	Scale factor used when generate look up table for
	Scale factor CE	8	13DH	Scale factor used when generate look up table for current even pixel multiplication
	Scale factor CE Scale factor CO	8	13DH 13EH	current even pixel multiplication
		-		current even pixel multiplication Scale factor used when generate look up table for
		-		current even pixel multiplication

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	Scale factor NO	8	140H	Scale factor used when generate look up table for next odd pixel multiplication			
	Offset factor CE	8	141H	Offset factor used when generate look up table for current even pixel multiplication			
	Offset factor CO	8	142H	Offset factor used when generate look up table for current odd pixel multiplication			
	Offset factor NE	8	143H	Offset factor used when generate look up table for next even pixel multiplication			
	Offset factor NO	8	144H	Offset factor used when generate look up table for next odd pixel multiplication			
m	Scale factor V	8	145H	Scale factor used when generate look up table for line multiplication			
	Offset factor V	8	146H	Offset factor used when generate look up table for line multiplication			
	Minimum pixels per line for LCD	11	147H-148H	Minimum number of pixels per line for LCD panel			
	LCD polarity	4	149H[3:0]	Controls the polarity of output VSYNC, HSYNC, clock and display enable			
				Bit0: 0: clock active high, 1: clock active low Bit1: 0: HSYNC active low, 1: HSYNC active high			
				Bit2: 0: VSYNC active low, 1: VSYNC active high Bit4: 0: de active high, 1: de active low			
	Check sum	8	14AH	Sum of all part 9 bytes (keep only lower 8 bit)			

#### Part 10: Horizontal Interpolation Lookup Table

Symbol	Width (bits)	Address	Description
Mapped value	8		This is the base table for all four horizontal interpolation lookup tables. Each table is then generated by multiply this value with corresponding scale factor and added with corresponding offset factor.
Check Sum	8	2C0H	Sum of all part 10 entry (only keep lower 8 bits)

#### Part 11: Vertical Interpolation Lookup Table

Symbol	Width (bits)	Address	Description
Mapped value	8		This is the base table for vertical interpolation lookup table. The vertical interpolation table is then generated by multiply this value with vertical scale factor and added with vertical offset factor.
Check Sum	8	3E0H	Sum of all part 10 entry (only keep lower 8 bits)

#### **3.6. CPU interface**

The SD1200 supports 2-wire  $I^2C$  serial interface to external CPU. The interface allows external CPU to access and modify control registers inside the SD1200. The  $I^2C$  serial interface is similar to the EEPROM interface, and the CPU is the host that drives the SCL all the time as the clock and for "start" and "stop" bits. The SCL frequency can be as high as 5MHz. The SDA is a bi-directional data wire. This interface supports random and sequential write operations for CPU to modify one or multiple control registers, and random and sequential read operations for CPU to read all or part of the control registers.

The lower 4 bits of device ID for SD1200 are fixed at "1010". The upper 3 bits are programmable through MODE\_IN3 (pin 19), MODE\_IN2 (pin 18) and MODE\_IN1 (pin 15). This avoids any conflict with other I2C devices on the same bus.

The following table briefly describes the SD1200 control registers. External CPU can read these register to know the state of the SD1200 as well as the result of input mode detection and phase calibration. External CPU can modify these control registers to disable several SD1200 features and force the SD1200 into a particular state. When the CPU modifies the control registers, the new data will be first stored in a set of shadow registers, and then are copied into the actual control registers when the "CPU Control Enable" bit is set. When the "CPU Control Enable" bit is set, the external CPU will retain control and the SD1200 will not perform the auto mode detection and auto calibration.

The external CPU is able to adjust the size of the output image and move the output image up and down by simply changing the porch size and pixel and line numbers of the input signal. These adjustments can be tied to the external user control button on the monitor.

A set of four control registers are used to generate output signal when there is no input signal available to the SD1200, or the input signal is beyond the acceptable ranges. This operation mode is called standalone mode, which is very important for the end users when they accidentally select an input mode beyond the acceptable range of the SD1200, or when the input cable connection becomes loose for any reason. System

manufacturers can display appropriate OSD warning messages on the LCD panel to notify the users about the problem.

#### Table 3: SD1200 Control Registers

DataOha - title -	Symbol	Width	Mode	Address	Description
w.DataSheet4U.com	VBP Source	11	RW	0H-1H	Input VSYNC back porch (not include pulse width)
	VSIZE Source	11	RW	2H-3H	Input image lines per frame
	VTOTAL Source	11	RW	4H-5H	Input total number of lines including porches
	HBP Source	11	RW	6H-7H	Input HSYNC back porch (not include pulse
					width)
	HSIZE Source	11	RW	8H-9H	Input image pixels per line
	HTOTAL Source	11	RW	AH-BH	Input total number of pixels per line including porches
	Mode Source	3	RW	CH[2:0]	Input video format 0: 640x350 1: 640x400 2: 720x400 3: 640x480
					4: 800x600 5: 1024x768 6: 1280x1024 7: invalid
	Clock Phase Source	9	RW	DH-EH	Input sampling clock phase
	VPW standalone	10	RW	FH-10H	For standalone mode, the pulse width of VSYNC
	VTOTAL standalone	10	RW	11H-12H	For standalone mode, total number of line per frame
	HPW standalone	10	RW	13H-14H	For standalone mode, HSYNC active time in us
	HTOTAL standalone	10	RW	15H-16H	For standalone mode, HSYNC cycle time in us
	Disable auto calibration for mode	1	RW	17H[7]	Disable auto calibration for this mode 1: disable
	640x350				0: enable
	Delay auto calibration for mode 640x350	15	RW	17H[6:0]- 18H	The number of frames need to be skipped before starting auto calibration for this mode
	Disable auto calibration for mode 640x400	1	RW	19H[7]	Disable auto calibration for this mode 1: disable 0: enable
	Delay auto calibration for mode 640x400	15	RW	19H[6:0]- 1AH	The number of frames need to be skipped before starting auto calibration for this mode
	Disable auto calibration for mode 720x400	1	RW	1BH[7]	Disable auto calibration for this mode 1: disable 0: enable
	Delay auto calibration for mode 720x400	15	RW	1BH[6:0]- 1CH	The number of frames need to be skipped before starting auto calibration for this mode
	Disable auto calibration for mode 640x480	1	RW	1DH[7]	Disable auto calibration for this mode 1: disable 0: enable
	Delay auto calibration for mode 640x480	15	RW	1DH[6:0]- 1EH	The number of frames need to be skipped before starting auto calibration for this mode

	Disable auto	1	RW	1FH[7]	Disable auto calibration for this mode
	calibration for mode				1: disable
	800x600				0: enable
	Delay auto calibration for mode 800x600	15	RW	1FH[6:0]- 20H	The number of frames need to be skipped before starting auto calibration for this mode
	Disable auto	1	RW	2011 21H[7]	Disable auto calibration for this mode
	calibration for mode	1	κ.vv	216[7]	1: disable
	1024x768				0: enable
	Delay auto calibration	15	RW	21H[6:0]-	The number of frames need to be skipped before
	for mode 1024x768	15	IX W	2111[0.0]- 22H	starting auto calibration for this mode
m	Disable auto	1	RW	23H[7]	Disable auto calibration for this mode
	calibration for mode	1	IX VV	2311[7]	1: disable
	1280x1024				0: enable
	Delay auto calibration	15	RW	23H[6:0]-	The number of frames need to be skipped before
	for mode 1280x1024	15	IC	24H	starting auto calibration for this mode
	Disable auto	1	RW	25H[7]	Disable auto calibration for this mode
	calibration for mode	•	1000	2011[7]	1: disable
	INVALID				0: enable
	Delay auto calibration	15	RW	25[6:0]-	The number of frames need to be skipped before
	for mode INVALID			26H	starting auto calibration for this mode
	Bypass Sync Polarity	1	RW	27H[7]	Bypass Input SYNC polarity detection (default 0)
	JI man J have been specified as a sp				1: bypass input SYNC polarity detection
					0: detect input SYNC polarity and make them
					negative polarity
	Enable SYNC Check	7	RW	27H[6:0]	Enable SYNC polarity check during input mode
					detection (default all 0).
					1: enable SYNC polarity based mode detection
					0: disable SYNC polarity based mode detection
					bit 0: 640x350
					bit 1: 640x400
					bit 2: 720x400
					bit 3: 640x480
					bit 4: 800x600
					bit 5: 1024x768
	D'4 ' E 11	1	DW	0011171	bit 6: 1280x1024
	Dithering Enable	1	RW	28H[7]	Enable dithering for 6 bit panel (default 0)
					1: enable dithering
	Frame Modulation	1	DW	2011[2]	0: disable dithering Enable frame modulation for 6 bit panel (default
	Enable	1	RW	28H[6]	(default 0)
	Lilaute				1: enable frame modulation
					0: disable frame modulation
	Horizontal	1	RW	28H[5]	Enable horizontal interpolation (default 0)
	Interpolation Enable	1	IX W	2011[3]	1: enable horizontal interpolation
	Interpolation Enable				0: disable horizontal interpolation
	Vertical Interpolation	1	RW	28H[4]	Enable vertical interpolation (default 0)
	Enable				1: enable vertical interpolation
					0: disable vertical interpolation
	Horizontal Rounding	1	RW	28H[3]	Enable horizontal rounding (default 0)
	Enable				1: enable horizontal rounding
					0: disable horizontal rounding
	Vertical Rounding	1	RW	28H[2]	Enable vertical rounding (default 0)
	Enable				1: enable vertical rounding
					0: disable vertical rounding
	Horizontal Table	1	RW	28H[1]	Enable horizontal Table Lookup (default 0)

1					
	Lookup Enable				1: enable horizontal Table Lookup
		-	DUU	0011(0)	0: disable horizontal Table Lookup
	Vertical Table	1	RW	28H[0]	Enable vertical Table Lookup (default 0)
	Lookup Enable				1: enable vertical Table Lookup
					0: disable vertical Table Lookup
	HSYNC Threshold	1	RW	29H[4]	Enable detection of short lines (IBM panel only,
	Enable				default 0)
					1: Enable such detection
					0: disable such detection
	OSD Intensity	1	RW	29H[3]	OSD intensity selection
t4U.com					0: half intensity
					1: full intensity
	Load ALL EEPROM	1	RW	29H[2]	Should be kept low most time. A high pulse will
					force SD1200 to reload all EEPROM entries
	Load Mode	1	RW	29H[1]	Should be kept low most time. A high pulse will
	Dependent EEPROM				force SD1200 to reload mode dependent
					EEPROM entries
	CPU control enable	1	RW	29H[0]	External CPU control enable
					0: disable external CPU control. SD1200 can write
					control registers, but CPU only read control
					registers.
					1: enable external CPU control. CPU can
					read/write control registers. SD1200 cannot write
					control registers
	Status 0	8	R	2AH	Read only internal status registers
					1: indicate error status
					0: indicate normal status
					Bit 0: EEPROM vertical lookup table loading
					Bit 1: EERPOM horizontal lookup table loading
					Bit 2: EEPROM mode dependent entries loading
					Bit 3: EEPROM calibration entries loading
					Bit 4: input has too few lines
					Bit 5: no input video
					Bit 6: input data clock is too fast
					Bit 7: refresh rate exceed LCD panel specification
	Status 1	4	R	2BH[3:0]	Internal auto calibration state

## 4. ELECTRICAL SPECIFICATION

This section presents the electrical specifications of the SD1200.

#### 4.1. Absolute Maximum Ratings

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Symbol	Parameter	Rating	Units
VCC	Power Supply	-0.3 to 6.0	V
VIN	Input Voltage	-0.3 to VCC + 0.3	V
VOUT	Output Voltage	-0.3 to VCC +0.3	V
TSTG	Storage Temperature	-55 to 150	°C

### 4.2. Recommended Operating Conditions

Symbol	Parameter	Min.	Тур.	Max.	Units
VCC	Commercial Power Supply	4.75	5.0	5.25	V
VCC	Industrial Power Supply	4.5	5.0	5.5	V
VIN	Input Voltage	0	-	VCC	V
TJ	Commercial Junction Operating Temperature	0	25	115	°C
TJ	Industrial Junction Operating Temperature	-40	25	125	°C

## 4.3. General DC Characteristics

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units
IIL	Input Leakage	no pull – up or	-1		1	μΑ
	Current	pull - down				
IOZ	TRI-state Leakage		-10		10	μA
	Current					
CIN	Input Capacitance			3		ρF
COUT	Output capacitance			3		ρF
CBID3	Bi-directional			3		ρF
	buffer capacitance					

Note: The capacitance above does not include PAD capacitance and package capacitance. One can estimate pin capacitance by adding pad capacitance, which is about  $0.5 \ rF$  and the package capacitance

### 4.4. DC Electrical Characteristics for 3.3 V Operation

	< Comparison of the second sec	ecommended Operation C		$cc = 3.0 \approx$	5.0 <b>v</b> ,	IJ = 0 C lo	+113 C)
	Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units
	VIL	Input low voltage	CMOS			0.3*VCC	V
	VIH	Input high Voltage	CMOS	0.7*VCC			V
om	VT-	Schmitt trigger negative going threshold voltage	COMS		1.22		V
	VT+	Schmitt trigger positive going threshold voltage	COMS		2.08		V
	VOL	Output low voltage	IOH=2,4,8,12, 16,24 mA			0.4	V
	VOH	Output high voltage	IOH=2,4,8,12, 16,24 mA	2.4			V
	RI	Input pull-up /down resistance	VIL=0V or VIH=VCC		75		KΩ

(Under Recommended Operation Conditions and  $Vcc = 3.0 \sim 3.6V$ ,  $T_J = 0^{\circ}C$  to +115°C)

#### 4.5. DC Electrical Characteristics for 5V Operation

(Under F	Recommended Operation	Conditions and VC	L=4.73~3	.25,1J	$=0^{-1}C_{10} + 10^{-1}$	115°C)
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units
VIL	Input low voltage	COMS			0.3*VCC	V
VIH	Input high voltage	COMS	0.7*VCC			V
VIL	Input low voltage	TTL			0.8	V
VIH	Input high voltage	TTL	2.0			V
VT-	Schmitt trigger negative going threshold voltage	CMOS		1.84		V
VT+	Schmitt trigger Positive going threshold voltage	COMS		3.22		V
VT-	Schmitt trigger negative going threshold voltage	TTL		1.10		V
VT+	Schmitt trigger positive going threshold voltage	TTL		1.87		V
VOL	Output low voltage	IOL=2,4,8,16,24mA			0.4	V
VOH	Output high voltage	IOH=2,4,8,16,24 mA	3.5			V
RI	Input pull-up / down resistance	VIL=0V or VIH=VCC		50		KΩ

(Under Recommended Operation Conditions and VCC=4.75~5.25,TJ=0°C to
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## **5. PACKAGE DIMENSIONS**

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## 6. ORDER INFORMATION

	Order Code	Temperature	Package	Speed
www.DataSheet4U.com	SD1200	Commercial	160-pin PQFP	60MHz
		$0^{\circ}$ C ~ $70^{\circ}$ C	14 x 20 (mm)	

## SmartASIC, Inc. WORLDWIDE OFFICE

U.S.A. (Headquarter) 2674 N. First Street, Suite 112 San Jose, CA 95134 U.S.A. Tel : 1-408-383-1818 Fax : 1-408-383-1819 Asia Pacific 13F, No. 11, Chung-Shan N. RD. Taipei, Taiwan R.O.C. Tel : 886-2-2542-5169 Fax : 886-2-2542-5166

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