## M50224FP <br> 1.5 Channel Motor Driver-with DC/DC Control

## Description

M50224FP is the semiconductor integrated circuit which builds in the Motor drive circuit and DC/DC circuit suitable for the camera etc.
1.5 H bridges, the $\mathrm{DC} / \mathrm{DC}$ circuit of $5 \mathrm{VDC} / \mathrm{DC}$, and AE operation circuit were built in one tip by adoption of a detailed CMOS process.

The reduction in power consumption and the miniaturization are considered as the high composition of the flexibility realized with one chip.

## Features

- Minute CMOS process acceptance.Low consumption
- 1.5 full swing voltage drive H Bridge circuit built-in (PWM drive correspondence)
- DC/DC circuit built-in of 5 V
- One AE operation circuit built-in AE (A sensor corresponds to amorphous and SPD)
- Low voltage incorrect operation prevention circuit thermole shutdown circuit built-in
- A thermometer, with a power save function


## Application

motor driver for cameras etc

## Recommend Operating Condition

Supply voltage range........ VB: 1.6 V to 3.5 V
Rated supply voltage VB:3.0V

## Pin Configuration



## Block Diagram



## Absolute Maximum Ratings

( $\mathrm{Ta}=25^{\circ} \mathrm{C}$, unless otherwise noted)

| Parameter | Symbol | Ratings | Unit | Remark |
| :--- | :--- | :--- | :--- | :--- |
| Supply voltage1 | VB | 3.5 | V | Note1 |
| Supply voltage2 | VDD | 6.5 | V | Note1 |
| Supply voltage3 | VDDH | VB+4.5 | V | Note1 |
| Voltage between BCIN and PGBC | VDSS | 15 | V | Note1 $(\mathrm{VGS}=0 \mathrm{~V})$ |
| Power dissipation | Pd | 1000 | mW | Note2 $\left(\mathrm{Ta}=25^{\circ} \mathrm{C}\right)$ |
| Thermal derating | $\mathrm{K} \theta$ | -8.0 | $\mathrm{~mW} /{ }^{\circ} \mathrm{C}$ | Note2 $\left(\mathrm{Ta} \geq 25^{\circ} \mathrm{C}\right)$ |
| Pin input Voltage | Vin | 0 to VDD +0.3 | V | Note3 |
| Operating temperature | Topr | -10 to 50 | ${ }^{\circ} \mathrm{C}$ |  |
| Storage temperature | Tstg | -40 to 150 | ${ }^{\circ} \mathrm{C}$ |  |

note1: As a principle, do not provide reversely
note2: Glass epoxy circuit board: $70 \mathrm{~mm} \times 70 \mathrm{~mm} \times 1.6 \mathrm{~mm}$ 1layer circuit board Cu Share $10 \%$
note3: As a principle, do not provide over supply voltage or under ground voltage

## Thermal Derating (Maximum Rating)

THERMAL DERATING (MAXIMUM RATING)


Remark
Calculation of power dissipation
Case : lout $\times$ lout $\times$ On resistance[transistor]
*Please refer to the above figure in the case that surroundings temperature exceeded $25^{\circ} \mathrm{C}$
*Please add the radiation board, if it is necessary.

I/O Circuit Diagram


## Electrical Characteristics

|  | Parameter | Symbol | Test condition | Limits |  |  | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | MIN | TYP | MAX |  |  |
|  | Voltage range of operation | VB |  | 2.0 | 3.0 | 3.5 | V |  |
|  | Current at the time of standby | IB1 | SEL1:L SEL2:L SEL3:L | - | 0.1 | 5 | $\mu \mathrm{A}$ |  |
|  | Usual consuming current 1 | IDD1 | Only a DC/DC circuit is turned ON. <br> SEL1:H SEL2:L SEL3 :L | - |  |  | mA |  |
|  | Usual consuming current 2 | IDD2 | DC/DC+AE+MD circuit ON SEL1:H SEL2:L SEL3 :H | - |  |  | mA |  |
|  | Hi level input current | IIH | $\mathrm{VIN}=\mathrm{VDD}=5.0 \mathrm{~V}$ | 25 | 50 | 100 | $\mu \mathrm{A}$ | Note1 |
|  | Lo level input current | IIL |  | -1.0 | - | - | $\mu \mathrm{A}$ |  |
|  | Input pull down resistance | RIND |  | 50 | 100 | 200 | $\mathrm{K} \Omega$ |  |
|  | Hi level input voltage | VIH | $\mathrm{VDD}=4.5$ to 5.5 V | VDD $\times 0.7$ | - | VDD | V |  |
|  | Lo level input voltage | VIL | $\mathrm{VDD}=4.5$ to 5.5 V | 0 | - | VDD $\times 0.3$ | V |  |
|  | Oscillation frequency | fosc | VDD $=5.0 \mathrm{~V}$ | 44 | 63 | 82 | kHz | Note2 |
|  | DUTY | DUTY | VDD=5.0V |  | 75 |  | \% |  |
|  | Operating start Voltage | Vstart1 | VB voltage | - | - | 2.0 | V |  |
|  | Operating stop Voltage | Vstop1 | VB voltage | - | - | 1.0 | V |  |
|  | Output voltage | Vout | VDD voltage | 4.7 | 5.0 | 5.3 | V |  |
|  | Input stability | $\Delta$ Vout1 | $\mathrm{VB}=2.0 \mathrm{~V}$ to 3.3V IDD $=50 \mathrm{~mA}$ | - | - | 100 | mV |  |
|  | Load stability | $\Delta$ Vout2 | $\mathrm{VB}=2.85 \mathrm{~V}$ IDD $=100 \mathrm{~mA}$ | - | - | 100 | mV |  |
|  | Maximum output current | Iout | $\mathrm{VB}=2.85 \mathrm{~V} \mathrm{VDD} \geq 4.5 \mathrm{~V}$ | 100 | - | - | mA |  |
|  | Oscillation frequency | fosc2 | VDD=5.0V | 150 | 227 | 320 | kHz | Note3 |
|  | DUTY | DUTY2 | VDD=5.0V |  | 50 |  | \% |  |
|  | Operating start Voltage | Vstart2 | VDD voltage | 4.5 | 5.0 | 5.3 | V |  |
|  | Output voltage | Vout2 | VDDH voltage | VB+2.6 | VB+3.3 | VB+4.5 | V |  |
|  | Operating voltage | VBDCM | VB voltage | 1.6 | - | 3.5 | V |  |
|  | ON Resistance RVON 1 | RVON 1 | $\begin{aligned} & \mathrm{I} 0=0.5 \mathrm{~A}, \mathrm{VB}=3 \mathrm{~V}, \mathrm{VDD}=5 \mathrm{~V}, \\ & \mathrm{VDDH}=5.5 \mathrm{~V} \end{aligned}$ | - | 0.75 | 1.1 | $\Omega$ | Note4 |
|  | Maximum output current | Iomax | T < ***S | 1.8 | - | - | A |  |
|  | Continual maximum output current | locont |  | 500 | ${ }^{-}$ | - | mA |  |
|  | Turn on time | TvON | $\mathrm{RM}=5.0 \Omega$ | - | 0.5 | 2 | $\mu \mathrm{s}$ |  |
|  | Turn off time | TvOFF | Fig. 1 | - | 0.1 | 0.5 | $\mu \mathrm{s}$ |  |
|  | Output rise time Tr | Tr |  | - | 0.3 | 1.0 | $\mu \mathrm{s}$ |  |
|  | Output fall time Tf | Tvf |  | - | 0.01 | 0.2 | $\mu \mathrm{s}$ |  |


|  | Parameter | Symbol | Test condition | Limit |  |  | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | MIN | TYP | MAX |  |  |
|  | Temperature output absolute value | VTE |  | . | 2713 | 3392 | mV |  |
|  | Temperature output power supply voltage change 1 | dVTE1 | VDD=5.5V | -45 | - | 45 | mV |  |
|  | Temperature output power supply voltage change 2 | dVTE2 | VDD $=4.5 \mathrm{~V}$ | -45 | - | 45 | mV |  |
|  | Temperature output voltage load change | dVTE3 | $10=-0.2 \mathrm{~mA}$ | -20 | - | 20 | mV |  |
|  | The amount of temperature output change | dVTE4 | The Amount of Change (-10 to $50^{\circ} \mathrm{C}$ ) | -22.7 | -22.0 | -19.1 | mV |  |
|  | Input range | IA |  | 50p | - | 120u | A |  |
|  | Light measurement output absolute value | VAE | $\mathrm{IA}=10 \mathrm{nA}$ |  | 1914 |  | mV |  |
|  | The amount of change per two step | dEVA1 | $\mathrm{IA}=10 \mathrm{nA}->40 \mathrm{nA}$ |  | -242 |  | mV |  |
|  | Output linearity 1 | DEVS1 | $\mathrm{IA}=50 \mathrm{pA}$ to 1.6 nA | -30 | - | 30 | \% |  |
|  | Output linearity 2 | DEVS2 | $\mathrm{IA}=1.6 \mathrm{nA}$ to 410 nA | -23 | - | 23 | \% |  |
|  | Output linearity 3 | DEVS3 | $\mathrm{IA}=410 \mathrm{nA}$ to $13.1 \mu \mathrm{~A}$ | -23 | - | 23 | \% |  |
|  | Output linearity 4 | DEVS4 | $\mathrm{IA}=13.1 \mu \mathrm{~A}$ to $120 \mu \mathrm{~A}$ | -30 | - | 30 | \% |  |
|  | Power supply response | Trs | $\mathrm{IA}=50 \mathrm{pA}$ | - | - | 50 | ms |  |
| T S D | thermole shutdown temperature | TTSD | Tip temperature in case H bridge output turns off |  | 150 |  | ${ }^{\circ} \mathrm{C}$ | Note5 |

Note1: Input terminal : 11 to15 PIN
Note2: L=47 $\mu \mathrm{H}, \mathrm{C}=100 \mathrm{uF}$
Note3: Since it is a power supply only for the insides of IC, please do not connect a charge pump circuit to others.
Note4: The sum of upper and lower sides side ON resistance.
ON resistance is changed with VB, VDD, and VDDH voltage.

Note5: A shipment test is not performed although the TSD circuit characteristic presents reference data.


Fig 1 H bridge part switching characteristic waveform

## SEL Truth value table

| SEL1 | SEL2 | SEL3 | The contents of control |
| :--- | :--- | :--- | :--- |
| L | L | L | Standby |
| H | L | L | Only a DC/DC circuit is turned ON (*note) |
| H | L | H | DC/DC + AE circuit ON + motor1 contorol (AEOUT: right out) |
| H | H | H | DC/DC + AE circuit ON + motor2 contorol(AEOUT: right out) |
| H | H | L | DC/DC + AE circuit ON + shutter contorol(AEOUT : temperature out) |
| L | L | H | Only AE circuit ON (AEOUT: right out) |
| L | H | H | Only AE circuit ON (AEOUT: right out) |
| L | H | L | Only AE circuit ON (AEOUT : temperature out) |

*1. SEL1:DC/DC and Charge pump contorol (L=OFF, H=ON)


## Motor control Truth value table

|  | INPUT |  |  |  |  | MOTOR1 | MOTOR2 | Shutter | MOTOR Each output |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | SEL1 | SEL2 | SEL3 | SML1 | SML2 |  |  |  | OUT1 | OUT2 | OUT3 |
| MOTOR1 <br> Control | H | L | H | L | L | Standby | Standby | Standby | OFF | OFF | OFF |
|  | H | L | H | H | L | Forward Rotation | Standby | Standby | L | H | OFF |
|  | H | L | H | L | H | Reverse | Standby | Standby | H | L | OFF |
|  | H | L | H | H | H | Brake | Standby | Standby | H | H | OFF |
| MOTOR2 <br> Control | H | H | H | L | L | Standby | Standby | Standby | OFF | OFF | OFF |
|  | H | H | H | H | L | Standby | Forward Rotation | Standby | OFF | H | L |
|  | H | H | H | L | H | Standby | Reverse | Standby | OFF | L | H |
|  | H | H | H | H | H | Standby | Brake | Standby | OFF | H | H |
| Shutter Control | H | H | L | L | L | Standby | Standby | Standby | OFF | OFF | OFF |
|  | H | H | L | H | L | Standby | Standby | Forward <br> Rotation | OFF | OFF | L |
|  | H | H | L | L | H | Standby | Standby | Reverse | OFF | OFF | H |
|  | H | H | L | H | H | Standby | Standby | Brake | OFF | OFF | H |

*: Please pass through the Brake or Stand-by mode by all means in case of moving from forward rotation to Reverse rotation or from
Reverse rotation to forward rotation by the motor control.
(ex.) Forward rotation -> Brake -> Reverse rotation,Reverse rotation -> Stand-by -> Forward rotation

## Package Dimensions



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