

10 kPa On-Chip Temperature Compensated & Calibrated Silicon Pressure Sensors

The MPXM2010 device is a silicon piezoresistive pressure sensors providing a highly accurate and linear voltage output — directly proportional to the applied pressure. The sensor is a single, monolithic silicon diaphragm with the strain gauge and a thin-film resistor network integrated on-chip. The chip is laser trimmed for precise span and offset calibration and temperature compensation.

Features

- Temperature Compensated Over 0°C to +85°C
- Available in Easy-to-Use Tape & Reel
- Ratiometric to Supply Voltage
- Gauge Ported & Non Ported Options

Application Examples

- Respiratory Diagnostics
- Air Movement Control
- Controllers
- Pressure Switching

Figure 1 shows a block diagram of the internal circuitry on the stand-alone pressure sensor chip.

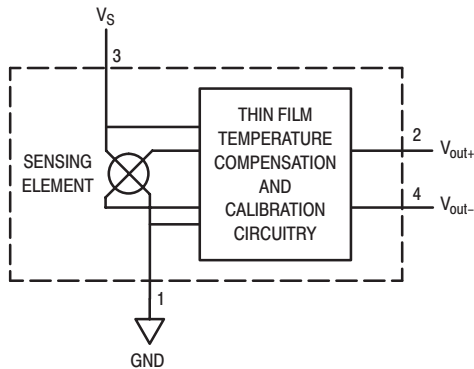


Figure 1. Temperature Compensated Pressure Sensor Schematic

VOLTAGE OUTPUT versus APPLIED DIFFERENTIAL PRESSURE

The differential voltage output of the sensor is directly proportional to the differential pressure applied.

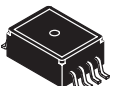
The output voltage of the differential or gauge sensor increases with increasing pressure applied to the pressure side (P1) relative to the vacuum side (P2). Similarly, output voltage increases as increasing vacuum is applied to the vacuum side (P2) relative to the pressure side (P1).

Preferred devices are Motorola recommended choices for future use and best overall value.

**MPXM2010
SERIES**

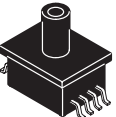
Motorola Preferred Device
**0 to 10 kPa (0 to 1.45 psi)
25 mV FULL SCALE SPAN
(TYPICAL)**

MPAK PACKAGE



SCALE 1:1

**MPXM2010D/DT1
CASE 1320**



SCALE 1:1

**MPXM2010GS/GST1
CASE 1320A**

PIN NUMBER			
1	Gnd	3	V _S
2	+V _{out}	4	-V _{out}

MPXM2010 SERIES

MAXIMUM RATINGS(NOTE)

Rating	Symbol	Value	Unit
Maximum Pressure (P1 > P2)	P _{max}	75	kPa
Storage Temperature	T _{stg}	-40 to +125	°C
Operating Temperature	T _A	-40 to +125	°C

NOTE: Exposure beyond the specified limits may cause permanent damage or degradation to the device.

OPERATING CHARACTERISTICS (V_S = 10 Vdc, T_A = 25°C unless otherwise noted, P1 > P2)

Characteristic	Symbol	Min	Typ	Max	Unit
Pressure Range ⁽¹⁾	P _{OP}	0	—	10	kPa
Supply Voltage ⁽²⁾	V _S	—	10	16	Vdc
Supply Current	I _o	—	6.0	—	mAdc
Full Scale Span ⁽³⁾	V _{FSS}	24	25	26	mV
Offset ⁽⁴⁾	V _{off}	-1.0	—	1.0	mV
Sensitivity	ΔV/ΔP	—	2.5	—	mV/kPa
Linearity ⁽⁵⁾	—	-1.0	—	1.0	%V _{FSS}
Pressure Hysteresis ⁽⁵⁾ (0 to 10 kPa)	—	—	±0.1	—	%V _{FSS}
Temperature Hysteresis ⁽⁵⁾ (-40°C to +125°C)	—	—	±0.5	—	%V _{FSS}
Temperature Effect on Full Scale Span ⁽⁵⁾	TCV _{FSS}	-1.0	—	1.0	%V _{FSS}
Temperature Effect on Offset ⁽⁵⁾	TCV _{off}	-1.0	—	1.0	mV
Input Impedance	Z _{in}	1000	—	2550	Ω
Output Impedance	Z _{out}	1400	—	3000	Ω
Response Time ⁽⁶⁾ (10% to 90%)	t _R	—	1.0	—	ms
Warm-Up	—	—	20	—	ms
Offset Stability ⁽⁷⁾	—	—	±0.5	—	%V _{FSS}

NOTES:

1. 1.0 kPa (kiloPascal) equals 0.145 psi.
2. Device is ratiometric within this specified excitation range. Operating the device above the specified excitation range may induce additional error due to device self-heating.
3. Full Scale Span (V_{FSS}) is defined as the algebraic difference between the output voltage at full rated pressure and the output voltage at the minimum rated pressure.
4. Offset (V_{off}) is defined as the output voltage at the minimum rated pressure.
5. Accuracy (error budget) consists of the following:
 - Linearity: Output deviation from a straight line relationship with pressure, using end point method, over the specified pressure range.
 - Temperature Hysteresis: Output deviation at any temperature within the operating temperature range, after the temperature is cycled to and from the minimum or maximum operating temperature points, with zero differential pressure applied.
 - Pressure Hysteresis: Output deviation at any pressure within the specified range, when this pressure is cycled to and from the minimum or maximum rated pressure, at 25°C.
 - TcSpan: Output deviation at full rated pressure over the temperature range of 0 to 85°C, relative to 25°C.
 - TcOffset: Output deviation with minimum rated pressure applied, over the temperature range of 0 to 85°C, relative to 25°C.
6. Response Time is defined as the time for the incremental change in the output to go from 10% to 90% of its final value when subjected to a specified step change in pressure.
7. Offset stability is the product's output deviation when subjected to 1000 hours of Pulsed Pressure, Temperature Cycling with Bias Test.

LINEARITY

Linearity refers to how well a transducer's output follows the equation: $V_{out} = V_{off} + \text{sensitivity} \times P$ over the operating pressure range. There are two basic methods for calculating nonlinearity: (1) end point straight line fit (see Figure 2) or (2) a least squares best line fit. While a least squares fit gives the "best case" linearity error (lower numerical value), the calculations required are burdensome.

Conversely, an end point fit will give the "worst case" error (often more desirable in error budget calculations) and the calculations are more straightforward for the user. Motorola's specified pressure sensor linearities are based on the end point straight line method measured at the midrange pressure.

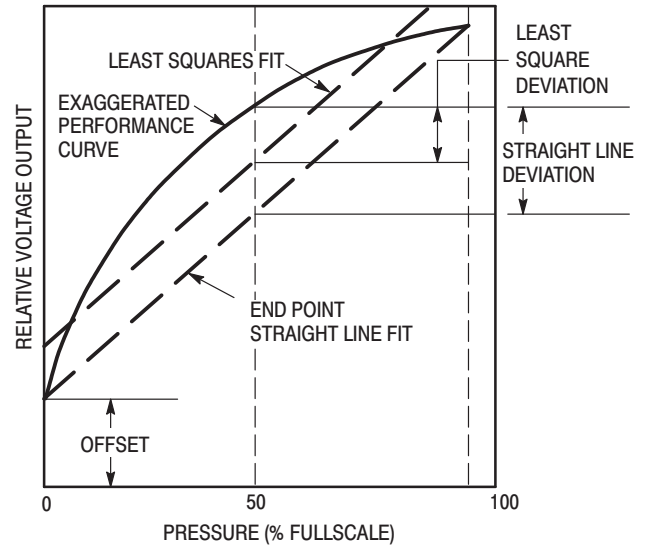


Figure 2. Linearity Specification Comparison

ON-CHIP TEMPERATURE COMPENSATION and CALIBRATION

Figure 3 shows the minimum, maximum and typical output characteristics of the MPXM2010 series at 25°C. The output is directly proportional to the differential pressure and is essentially a straight line.

A silicone gel isolates the die surface and wire bonds from the environment, while allowing the pressure signal to be transmitted to the silicon diaphragm.

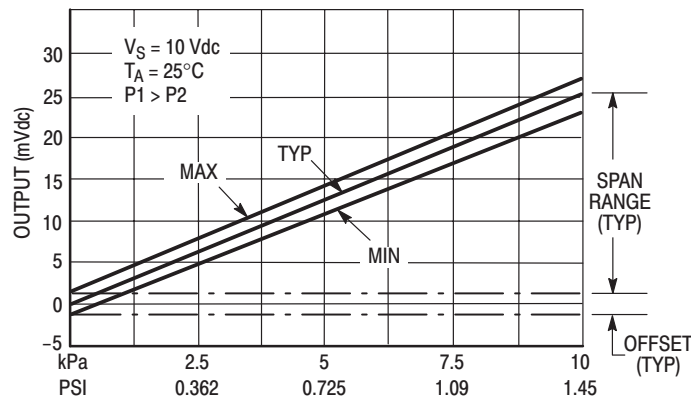
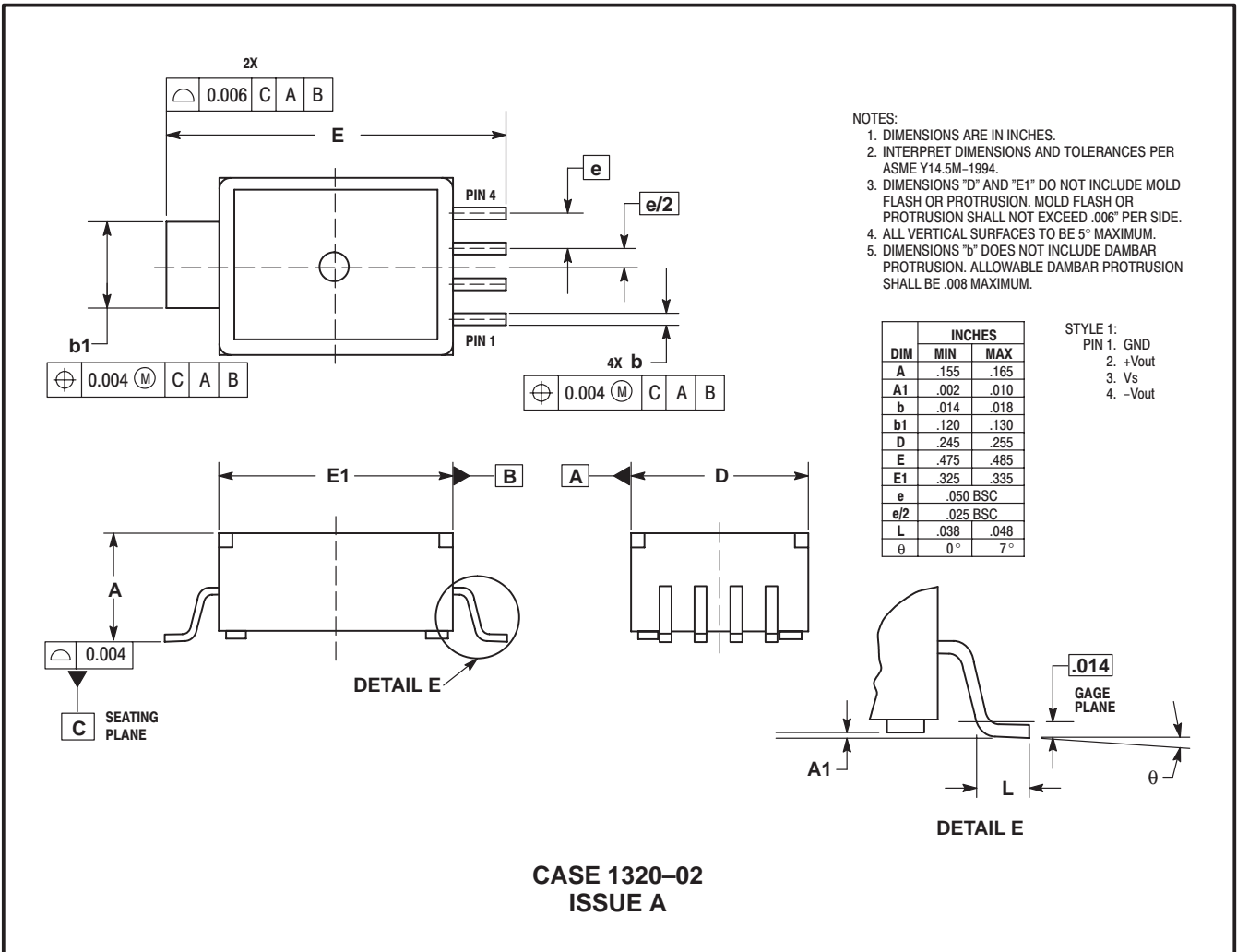
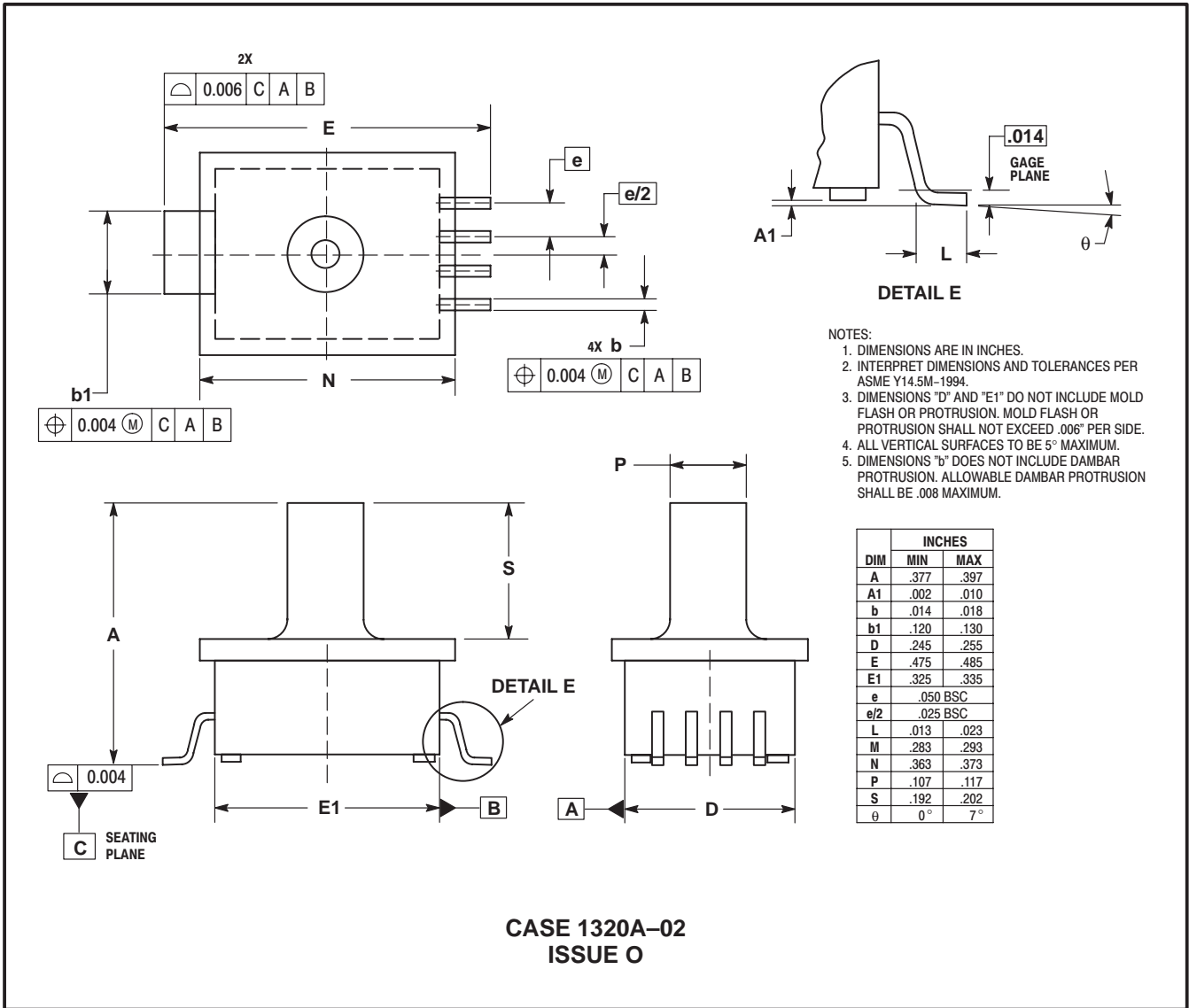


Figure 3. Output versus Pressure Differential

ORDERING INFORMATION		
Device Type	Options	Case No.
MPXM2010D	Non–ported	1320
MPXM2010DT1	Non–ported, Tape and Reel	1320
MPXM2010GS	Ported	1320A
MPXM2010GST1	Ported, Tape and Reel	1320A

PACKAGE DIMENSIONS





- NOTES:
1. DIMENSIONS ARE IN INCHES.
 2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5M-1994.
 3. DIMENSIONS "D" AND "E1" DO NOT INCLUDE MOLD FLASH OR PROTRUSION. MOLD FLASH OR PROTRUSION SHALL NOT EXCEED .006" PER SIDE.
 4. ALL VERTICAL SURFACES TO BE 5° MAXIMUM.
 5. DIMENSIONS "b" DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE .008 MAXIMUM.

DIM	INCHES	
	MIN	MAX
A	.377	.397
A1	.002	.010
b	.014	.018
b1	.120	.130
D	.245	.255
E	.475	.485
E1	.325	.335
e	.050 BSC	
e/2	.025 BSC	
L	.013	.023
M	.283	.293
N	.363	.373
P	.107	.117
S	.192	.202
θ	0°	7°

CASE 1320A-02
ISSUE O

NOTES

NOTES

MPXM2010 SERIES

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MPXM2010/D